

Universal algebra for CSP

Lecture 2

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Exactly one of the following conditions holds:

- 1 There exists a reflexive not-symmetric digraph \mathbb{G} which is compatible with some member of $\text{HSP}(\mathbf{A})$; or
- 2 There exists $f \in \mathcal{C}_{[3]}$ which satisfies $f(x, x, y) \approx y$ and $f(x, y, y) \approx x$.

In case (1), the proof found such \mathbb{G} compatible with $\mathbf{F} \leq \mathbf{A}^{|A|^2}$.

Question raised: do we really need to look that ‘deeply’ into $\text{HSP}(\mathbf{A})$?

Example. For any finite set A , the *Stupecki clone* \mathcal{S}_A on A is the union of:

- {all operations that depend on at most one variable},
- {all operations that are not surjective}.

Let $\mathbf{A} = (A; \mathcal{S}_A)$. Clearly \mathbf{A} is not in case (2).

Exercise: if $|A| > 2n$, show that no member of $\text{HS}(\mathbf{A}^n)$ has a reflexive not-symmetric compatible digraph.

Fixed-Template Constraint Satisfaction Problems

Fix a relational structure $\mathbb{G} = (A; \mathcal{R})$ with A and \mathcal{R} finite.

Definition

$\text{CSP}(\mathbb{G})$ is either of the following equivalent decision problems:

Constraints version

Input: Set V of variables, “constraints” on tuples of variables (requiring them to belong to prescribed relations in \mathcal{R}).

Query: Is there an assignment $V \rightarrow A$ which satisfies all the constraints?

Homomorphism version

Input: a finite relational structure $\mathbb{H} = (B, \mathcal{S})$ of the same “signature” as \mathbb{G} .

Query: Does there exist a homomorphism $\mathbb{H} \rightarrow \mathbb{G}$?

Archetypal examples

$\mathbb{G}_1 = (\{0, 1\}; \{R_{abc} : a, b, c \in \{0, 1\}\})$ where

$$R_{abc} = \{0, 1\}^3 \setminus \{(a, b, c)\}.$$

E.g., the constraint “ $(x, y, z) \in R_{101}$ ” says “ $\neg x$ or y or $\neg z$.”

$\text{CSP}(\mathbb{G}_1)$ is equivalent to 3-SAT, which is *NP*-complete.

$\mathbb{G}_2 = (\{0, 1\}; \{S_0, S_1\})$ where

$$S_0 = \{(x, y, z) : x \oplus y \oplus z = 0\}$$

$$S_1 = \{(x, y, z) : x \oplus y \oplus z = 1\}.$$

Instances of $\text{CSP}(\mathbb{G}_2)$ are systems of linear equations (each in 3 variables) over \mathbb{Z}_2 .

Such systems can be checked for consistency by Gaussian elimination; thus $\text{CSP}(\mathbb{G}_2)$ is in *P*.

$\mathbb{G}_4 = (\{0, 1\}; \{LE, C_0, C_1\})$ where

$$LE = \{(0, 0), (0, 1), (1, 1)\}$$

$$C_0 = \{0\}$$

$$C_1 = \{1\}.$$

Instances of $\text{CSP}(\mathbb{G}_4)$ can only “say” $x \leq y$, $x = 0$, or $x = 1$.

There is only one way to get a contradiction: by saying

$$x_1 = 1 \text{ and } x_n = 0 \text{ and } x_1 \leq x_2 \text{ and } x_2 \leq x_3 \text{ and } \dots \text{ and } x_{n-1} \leq x_n.$$

$\text{CSP}(\mathbb{G}_4)$ is equivalent to REACHABILITY, which is in P (in fact, in NL).

$\mathbb{G}_3 = (\{0, 1\}; \{=, C_0, C_1\})$.

Similar to \mathbb{G}_4 , but “undirected.”

$\text{CSP}(\mathbb{G}_3)$ encodes Undirected REACHABILITY, which is in L (Reingold, 2005).

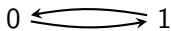
$$\mathbb{G}_5 = (\{0, 1\}; \{R_{110}, C_0, C_1\}).$$

“($x, y, z \in R_{110}$ ” is equivalent to “(x and y) implies z .”

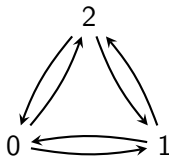
Similar to \mathbb{G}_4 , but with directed paths replaced by directed binary trees.

$\text{CSP}(\mathbb{G}_5)$ is equivalent to Horn 3-SAT, which is P -complete.

$$\mathbb{K}_n = (A; \{\neq_A\}) \text{ where } A = \{0, 1, \dots, n-1\}.$$



\mathbb{K}_2

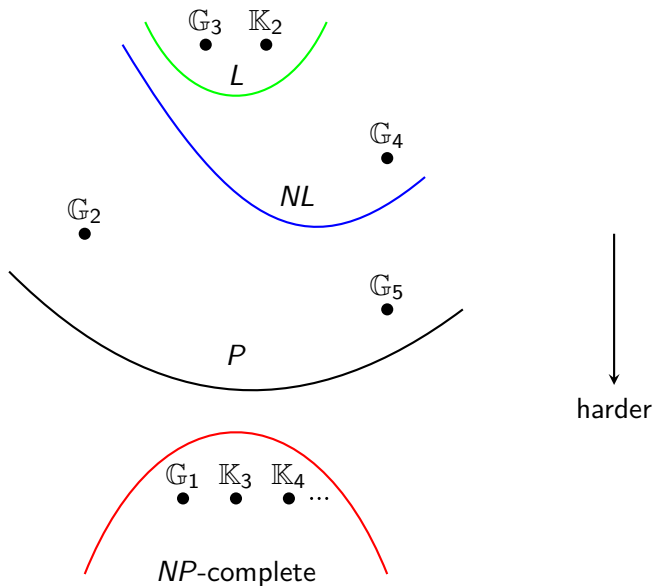


\mathbb{K}_3

$\text{CSP}(\mathbb{K}_n)$ is equivalent to n -COLOURABILITY, which is

- NP -complete for $n \geq 3$, and
- In P (in fact, in L) if $n = 2$.

Summary:



Comparing CSPs

We will use the following tools:

- 1 Simulations, pp-definitions
- 2 Polymorphisms
- 3 Reduction to the “idempotent case”
- 4 Algebraic substructures, Pp-constructions

Simulation

Consider again $\mathbb{G}_5 = (\{0, 1\}; R_{110}, C_0, C_1)$.

Suppose we modify \mathbb{G}_5 by adding $R_{1110} = \{0, 1\}^4 \setminus \{(1, 1, 1, 0)\}$:

$$\mathbb{G}'_5 = (\{0, 1\}; R_{110}, C_0, C_1, R_{1110}).$$

Is $\text{CSP}(\mathbb{G}'_5)$ harder than $\text{CSP}(\mathbb{G}_5)$?

NO! R_{110} can simulate R_{1110} as follows:

- “ $(x, y, z, w) \in R_{1110}$ ” means “ $(x \ \& \ y \ \& \ z) \Rightarrow w$.”
- Given any constraint $(x \ \& \ y \ \& \ z) \Rightarrow w$, introduce a new variable t and replace the constraint with two new constraints

$$(x \ \& \ y) \Rightarrow t \quad \text{and} \quad (t \ \& \ z) \Rightarrow w.$$

Key: $R_{1110}(x, y, z, w)$ is defined in \mathbb{G}_5 by $\exists t[R_{110}(x, y, t) \ \& \ R_{110}(t, z, w)]$.

Pp-definability

In general:

Definition

- 1 A *primitive positive (pp)* formula is any first-order formula of the form

$$\exists \dots \left[\bigwedge_i \text{atomic}_i \right]$$

where each *atomic_i* is a basic relation or equality ($x = y$).

- 2 Given a relational structure $\mathbb{G} = (A; \mathcal{R})$ and a relation S on A , we say that S is *pp-definable in \mathbb{G}* if there exist a pp-formula using relations from \mathcal{R} whose set of solutions in \mathbb{G} is S .

Theorem (Folklore; Larose & Tesson 2007)

Suppose \mathbb{G}, \mathbb{H} are finite relational structures with the same domain. If every relation of \mathbb{H} is pp-definable in \mathbb{G} , then $\text{CSP}(\mathbb{H}) \leq_L \text{CSP}(\mathbb{G})$.

Testing pp-definability

How can we test whether a relation is pp-definable in a structure?

Theorem (Bodnarčuk et al; Geiger 1968)

Let $\mathbb{G} = (A; \mathcal{R})$ with A *finite*, and let E be an n -ary relation on A . TFAE:

- 1 E is pp-definable in \mathbb{G} .
- 2 E is compatible with every polymorphism of \mathbb{G} .

Proof sketch (2) \Rightarrow (1) ...

Corollary

If \mathbb{G}, \mathbb{H} are finite relational structures with the same domain and the same polymorphisms, then $\text{CSP}(\mathbb{G})$ and $\text{CSP}(\mathbb{H})$ have the same complexity.

Proof ...

Polymorphism algebra of a structure

Definition

Given a finite relational structure $\mathbb{G} = (A; \mathcal{R})$, the *polymorphism algebra* of \mathbb{G} is the algebra

$$\text{PolAlg}(\mathbb{G}) = (A; \text{Pol}(\mathbb{G}))$$

where $\text{Pol}(\mathbb{G}) = \{\text{all polymorphisms of } \mathbb{G}\}$.

By previous slide, $\text{PolAlg}(\mathbb{G})$ determines the complexity of $\text{CSP}(\mathbb{G})$.

This is the first insight of the “Algebraic approach” to CSP.

Examples revisited

$\mathbb{G}_1 = (\{0, 1\}; \{R_{abc} : a, b, c \in \{0, 1\}\})$ where

$$R_{abc} = \{0, 1\}^3 \setminus \{(a, b, c)\}.$$

$\text{Pol}(\mathbb{G}_1) = \{\text{projections}\}$. (Exercise: prove it!)

$\text{PolAlg}(\mathbb{G}_1) = (\{0, 1\}; \{\text{proj's}\}) \text{ " = " } (\{0, 1\}; \emptyset) = \text{the 2-element set!}$

$\mathbb{G}_2 = (\{0, 1\}; \{\text{"x} \oplus y \oplus z = 0,\text{" "x} \oplus y \oplus z = 1\}\})$.

$\text{Pol}(\mathbb{G}_2) = \{\text{all boolean sums of an odd number of variables}\} =: \mathbb{C}_2$.

$\text{PolAlg}(\mathbb{G}_2) = (\{0, 1\}; \mathbb{C}_2) \text{ " = " } (\{0, 1\}; x \oplus y \oplus z) = \text{like a vector space!}$

$\mathbb{G}_4 = (\{0, 1\}; \{LE, C_0, C_1\})$ where $LE = \{(0, 0), (0, 1), (1, 1)\}$.

$\text{Pol}(\mathbb{G}_4) = \{f : f \text{ is monotone and "idempotent"}\} =: \mathcal{C}_4$.

("Idempotent" means $f(0, 0, \dots, 0) = 0$ and $f(1, 1, \dots, 1) = 1$.)

$\text{PolAlg}(\mathbb{G}_4) = (\{0, 1\}; \mathcal{C}_4) \text{ "=" } (\{0, 1\}; \max, \min) = \text{the 2-element lattice!}$

$\mathbb{G}_3 = (\{0, 1\}; \{=, C_0, C_1\})$.

$\text{Pol}(\mathbb{G}_3) = \{\text{all idempotent boolean functions}\} =: \mathcal{C}_3$.

$\text{PolAlg}(\mathbb{G}_3) = (\{0, 1\}; \mathcal{C}_3) = \text{almost a boolean algebra!}$

$$\mathbb{G}_5 = (\{0, 1\}; \{R_{110}, C_0, C_1\}).$$

(Recall that $\text{CSP}(\mathbb{G}_5)$ encodes Horn 3-SAT, which is in P .)

Exercise:

- 1 Every $f \in \text{Pol}(\mathbb{G}_5)$ is monotone and idempotent.
- 2 $\min \in \text{Pol}(\mathbb{G}_5)$ but $\max \notin \text{Pol}(\mathbb{G}_5)$. (Exercise: prove it.)

$\text{PolAlg}(\mathbb{G}_5)$ “=” $(\{0, 1\}; \min)$ = the 2-element semi-lattice!

\mathbb{K}_n . For $n \geq 3$,

- $\text{Pol}(\mathbb{K}_n) = \{\text{permutations (in a single variable)}\}$.
- I.e., $\text{PolAlg}(\mathbb{K}_n)$ is a set with permutations.

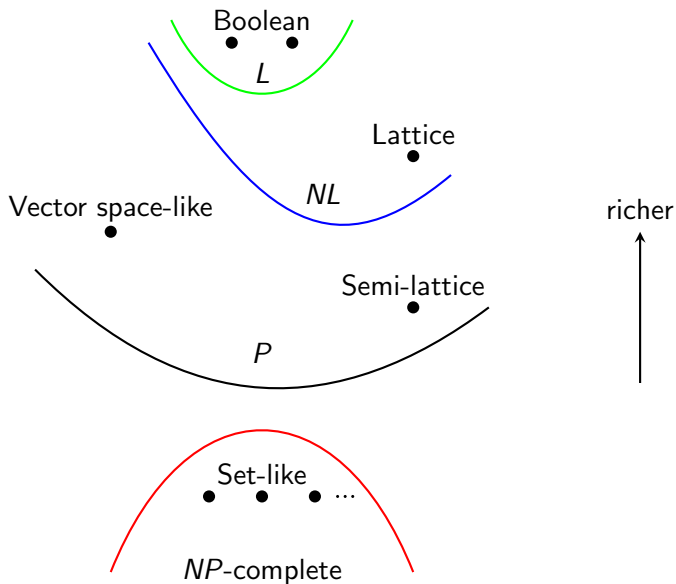
$\text{Pol}(\mathbb{K}_2)$ is much richer:

- 1 Consists of all “self-dual” functions, i.e., functions f which satisfy

$$f(\neg x_1, \neg x_2, \dots, \neg x_n) \approx \neg f(x_1, \dots, x_n).$$

- 2 Includes $x \oplus y \oplus z$ (which is a “Maltsev” operation), $\text{maj}(x, y, z)$, etc.
Almost a boolean algebra!

Polymorphism algebras as measure of CSP:



Core and idempotent structures

Let $\mathbb{G} = (A, \mathcal{R})$ be a finite structure.

Definition

- 1 \mathbb{G} is *core* if every endomorphism $f : \mathbb{G} \rightarrow \mathbb{G}$ is a bijection.
- 2 \mathbb{G} is *idempotent* if \mathcal{R} contains the relation $C_a = \{a\}$ for every $a \in A$.

Remarks:

- 1 \mathbb{G} is core iff all its 1-ary polymorphisms are permutations.
- 2 \mathbb{G} is idempotent $\Rightarrow \text{PolAlg}(\mathbb{G})$ is an idempotent algebra \Leftrightarrow every C_a is pp-definable in $\mathbb{G} \Leftrightarrow$ the identity map is the only 1-ary polymorphism of \mathbb{G} .
- 3 For every finite \mathbb{G} there exists an induced substructure \mathbb{G}' which is core and for which there exists a *retract* mapping \mathbb{G} onto \mathbb{G}' .
 - ▶ This \mathbb{G}' is unique up to isomorphism, and is called *the core of \mathbb{G}* .
- 4 $\mathbb{G}^c := (A; \mathcal{R} \cup \{C_a : a \in A\})$; it is idempotent.

Lemma

If \mathbb{G} is finite and $\text{core}(\mathbb{G})$ is its core, then $\text{CSP}(\mathbb{G}) \equiv \text{CSP}(\text{core}(\mathbb{G}))$.

Proof: An input maps homomorphically to \mathbb{G} iff it maps homomorphically to $\text{core}(\mathbb{G})$.

Lemma (???, Larose & Tesson 2007)

Suppose \mathbb{G} is core. Then $\text{CSP}(\mathbb{G}) \equiv_L \text{CSP}(\mathbb{G}^c)$.

Proof: it suffices to reduce $\text{CSP}(\mathbb{G}^c)$ to $\text{CSP}(\mathbb{G})$. There is a trick to do this.

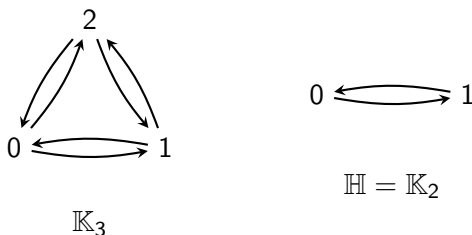
Conclusion: For CSP, we always assume the template \mathbb{G} is idempotent.

Algebraic substructures

Definition

Let $\mathbb{G} = (A; \mathcal{R})$ be a finite structure and $\mathbb{H} = (B; \mathcal{R}|_B)$ an induced substructure. We say that \mathbb{H} is an *algebraic substructure* of \mathbb{G} if B is (the domain of) a subalgebra of $\text{PolAlg}(\mathbb{G})$.

Example:



\mathbb{H} is **not** an algebraic substructure of \mathbb{K}_3 .

Observe: if $\mathbb{H} = (B; \dots)$ is an algebraic substructure of \mathbb{G} , then

- B is preserved by all polymorphisms of \mathbb{G} ...
- ... so B is pp-definable in \mathbb{G} .

More generally, given \mathbb{G} we will permit “substructures” whose:

- Domains are pp-definable subsets of G^2 (or G^3 , etc.) ...
- ... modulo pp-definable equivalence relations ...
- ... and whose relations need not be induced, merely pp-definable.

\mathbb{P}_p -constructible structures

Example: \mathbb{K}_3 .

Let Δ be the 3-ary relation defined by the formula

$$\delta(x, y, z) : (x \rightarrow y) \ \& \ (y \rightarrow z) \ \& \ (z \rightarrow x).$$

So

$$\Delta = \{(0, 1, 2), (1, 2, 0), (2, 0, 1), (2, 1, 0), (0, 2, 1), (1, 0, 2)\}.$$

Let E be the 6-ary relation defined by the formula $\varepsilon(x, y, z, x', y', z')$:

$$\begin{aligned} \exists x'', y'', z'' \quad [& \delta(x, y, z) \ \& \ \delta(x', y', z') \ \& \ \delta(x'', y'', z'') \ \& \\ & (x \rightarrow x'') \ \& \ (x'' \rightarrow x') \ \& \ (y \rightarrow y'') \ \& \ (y'' \rightarrow y') \\ & \ \& \ (z \rightarrow z'') \ \& \ (z'' \rightarrow z') \] \end{aligned}$$

$E = \{(0, 1, 2), (1, 2, 0), (2, 0, 1)\}^2 \cup \{(2, 1, 0), (0, 2, 1), (1, 0, 2)\}^2$, which is an equivalence relation on Δ (with two blocks).

Let R be the 6-ary relation defined by the formula

$$\exists x'', y'', z'' \quad [\delta(x, y, z) \ \& \ \delta(x', y', z') \ \& \ \delta(x'', y'', z'') \ \& \\ \varepsilon(x, y, z, x'', y'', z'') \ \& \\ (x' = x'') \ \& \ (y' = z'') \ \& \ (z' = y'') \] .$$

$$R = \{(0, 1, 2), (1, 2, 0), (2, 0, 1)\} \times \{(2, 1, 0), (0, 2, 1), (1, 0, 2)\} \cup \\ \{(2, 1, 0), (0, 2, 1), (1, 0, 2)\} \times \{(0, 1, 2), (1, 2, 0), (2, 0, 1)\} .$$

So $(\Delta/E; R/E) \cong \mathbb{K}_2$.

We say that \mathbb{K}_2 is *pp-constructible* from \mathbb{K}_3 via the above pp-formulas.

(Note from the audience: a simpler formula can define R .)

Let \mathbb{G}, \mathbb{H} be finite relational structures.

Write $\mathbb{G} = (A; \{\dots\})$ and $\mathbb{H} = (B; \{R_1, R_2, \dots\})$ with $\text{arity}(R_i) = n_i$.

General Definition

\mathbb{H} is **pp-constructible from** \mathbb{G} iff there exist:

- $k \geq 1$
- Pp-definable relations of \mathbb{G} :
 - ▶ $U \subseteq A^k$
 - ▶ $\Theta \subseteq U^2$ ($\subseteq (A^k)^2 = A^{2k}$)
 - ▶ $S_i \subseteq U^{n_i}$ ($\subseteq (A^k)^{n_i} = A^{n_i k}$) for $i = 1, 2, \dots$

such that

- Θ is an equivalence relation on U .
- $\mathbb{H} \cong (U; S_1, S_2, \dots)/\Theta$.

Notation: $\mathbb{H} \leq_{ppc} \mathbb{G}$.

Theorem (Bulatov, Jeavons, Krokhin 2005; Larose, Tesson (2007))

Suppose \mathbb{G}, \mathbb{H} are finite structures. If \mathbb{H} is pp-constructible from \mathbb{G} , then $\text{CSP}(\mathbb{H}) \leq_L \text{CSP}(\mathbb{G})$.

Proof: similar to the proof that pp-definable relations can be simulated.

Corollary

If \mathbb{K}_3 (or $\mathbb{G}_1 = (\{0, 1\}; \{R_{abc} : abc \in \{0, 1\}^3\})$) is pp-constructible from \mathbb{G} , then $\text{CSP}(\mathbb{G})$ is NP-complete.

Theorem

Let \mathbb{G}, \mathbb{H} be finite relational structures. TFAE:

- 1 \mathbb{H} is pp-constructible from \mathbb{G} .
- 2 \mathbb{H} is compatible with some member of $\text{HSP}(\text{PolAlg}(\mathbb{G}))$.

Proof sketch (2) \Rightarrow (1). Write $\mathbb{G} = (A; \dots)$, $\mathbb{H} = (B; \{R_1, R_2, \dots, \})$.

Let $\mathbf{A} = \text{PolAlg}(\mathbb{G})$. Assume \mathbb{H} is compatible with $\mathbf{B} \in \text{HSP}(\mathbf{A})$.

WLOG, $\mathbf{B} = \mathbf{U}/E$ for some $\mathbf{U} \in \text{SP}(\mathbf{A})$ and some congruence E of \mathbf{U} .

Say $\mathbf{U} \leq \mathbf{A}^k$. We can view $E \subseteq A^{2k}$.

Similarly, we can “pull back” each n -ary relation R_i to a kn -ary relation R_i^* on A .

All of $U, E, R_1^*, R_2^*, \dots$ are compatible with \mathbf{A} .

Hence they are all pp-definable in $\mathbb{G} \dots$

\dots and give a pp-construction of \mathbb{H} from \mathbb{G} . □

Corollary

For a finite relational structure \mathbb{G} , TFAE:

- 1 $\mathbb{G}_1 = (\{0, 1\}; \{R_{abc} : abc \in \{0, 1\}^3\})$ is pp-constructible from \mathbb{G} .
- 2 $\text{HSP}(\text{PolAlg}(\mathbb{G}))$ contains the 2-element set $(\{0, 1\}; \emptyset)$.

If either holds, $\text{CSP}(\mathbb{G})$ is NP-complete.

The **Algebraic Dichotomy Conjecture**, due to Bulatov, Jeavons and Krokhin, states:

Conjecture: If \mathbb{G} is *idempotent* and neither condition above holds, then $\text{CSP}(\mathbb{G})$ is in P .