

RELAXED VARIATIONAL PRINCIPLE FOR WATER WAVE MODELING

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Workshop on Ocean Wave Dynamics



ACKNOWLEDGEMENTS

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TALK IS MAINLY BASED ON:

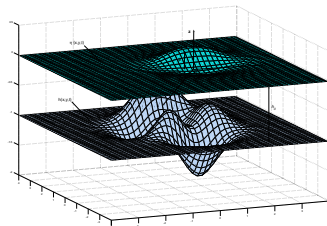
Clamond, D., Dutykh, D. (2012). *Practical use of variational principles for modeling water waves*. *Physica D: Nonlinear Phenomena*, 241(1), 25-36.

WATER WAVE PROBLEM - I

PHYSICAL ASSUMPTIONS:

- ▶ Fluid is ideal
- ▶ Flow is incompressible
- ▶ ... and irrotational, i.e. $\mathbf{u} = \nabla\phi$
- ▶ Free surface is a graph
- ▶ Above free surface there is void
- ▶ Atmospheric pressure is constant

Surface tension can be also taken into account



WATER WAVE PROBLEM - II

- ▶ Continuity equation

$$\nabla_{\mathbf{x},y}^2 \phi = 0, \quad (\mathbf{x}, y) \in \Omega \times [-d, \eta],$$

- ▶ Kinematic bottom condition

$$\frac{\partial \phi}{\partial y} + \nabla \phi \cdot \nabla d = 0, \quad y = -d,$$

- ▶ Kinematic free surface condition

$$\frac{\partial \eta}{\partial t} + \nabla \phi \cdot \nabla \eta = \frac{\partial \phi}{\partial y}, \quad y = \eta(\mathbf{x}, t),$$

- ▶ Dynamic free surface condition

$$\frac{\partial \phi}{\partial t} + \frac{1}{2} |\nabla_{\mathbf{x},y} \phi|^2 + g\eta + \sigma \nabla \cdot \left(\frac{\nabla \eta}{\sqrt{1 + |\nabla \eta|^2}} \right) = 0, \quad y = \eta(\mathbf{x}, t).$$



HAMILTONIAN STRUCTURE

ZAKHAROV (1968) [ZAK68]; CRAIG & SULEM (1993) [CS93]

CANONICAL VARIABLES:

$\eta(\mathbf{x}, t)$: free surface elevation

$\tilde{\phi}(\mathbf{x}, t)$: velocity potential at the free surface

$$\tilde{\phi}(\mathbf{x}, t) := \phi(\mathbf{x}, y = \eta(\mathbf{x}, t), t)$$

- ▶ Evolution equations:

$$\rho \frac{\partial \eta}{\partial t} = \frac{\delta \mathcal{H}}{\delta \tilde{\phi}}, \quad \rho \frac{\partial \tilde{\phi}}{\partial t} = -\frac{\delta \mathcal{H}}{\delta \eta},$$

- ▶ Hamiltonian:

$$\mathcal{H} = \int_{-d}^{\eta} \frac{1}{2} |\nabla_{\mathbf{x}, y} \phi|^2 dy + \frac{1}{2} g \eta^2 + \sigma \left(\sqrt{1 + |\nabla \eta|^2} - 1 \right)$$

LUKE'S VARIATIONAL PRINCIPLES

J.C. LUKE, JFM (1967) [LUK67]

- ▶ First improvement of the classical Lagrangian $\mathcal{L} := K + \Pi$:

$$\mathcal{L} = \int_{t_1}^{t_2} \int_{\Omega} \rho \mathcal{L} \, d\mathbf{x} \, dt, \quad \mathcal{L} := \int_{-d}^{\eta} (\phi_t + \frac{1}{2} |\nabla_{\mathbf{x},y} \phi|^2 + gy) \, dy$$

$$\delta\phi: \Delta\phi = 0, \quad (\mathbf{x}, y) \in \Omega \times [-d, \eta],$$

$$\delta\phi|_{y=-d}: \frac{\partial\phi}{\partial y} + \nabla\phi \cdot \nabla d = 0, \quad y = -d,$$

$$\delta\phi|_{y=\eta}: \frac{\partial\eta}{\partial t} + \nabla\phi \cdot \nabla\eta - \frac{\partial\phi}{\partial y} = 0, \quad y = \eta(\mathbf{x}, t),$$

$$\delta\eta: \frac{\partial\phi}{\partial t} + \frac{1}{2} |\nabla\phi|^2 + g\eta = 0, \quad y = \eta(\mathbf{x}, t).$$

- ▶ We recover the water wave problem by computing variations w.r.t. η and ϕ

GENERALIZATION OF THE LAGRANGIAN DENSITY

D. CLAMOND & D. DUTYKH, PHYS. D (2012) [CD12]

- ▶ Introduce notation (traces):

$\tilde{\phi} := \phi(\mathbf{x}, y = \eta(\mathbf{x}, t), t)$: quantity at the free surface

$\check{\phi} := \phi(\mathbf{x}, y = -d(\mathbf{x}, t), t)$: value at the bottom

- ▶ Equivalent form of Luke's lagrangian:

$$\mathcal{L} = \tilde{\phi}\eta_t + \check{\phi}d_t - \frac{1}{2}g\eta^2 + \frac{1}{2}gd^2 - \int_{-d}^{\eta} \left[\frac{1}{2}|\nabla\phi|^2 + \frac{1}{2}\phi_y^2 \right] dy$$

- ▶ Explicitly introduce the velocity field: $\mathbf{u} = \nabla\phi$, $v = \phi_y$

$$\mathcal{L} = \tilde{\phi}\eta_t + \check{\phi}d_t - \frac{1}{2}g\eta^2 - \int_{-d}^{\eta} \left[\frac{1}{2}(\mathbf{u}^2 + v^2) + \mu \cdot (\nabla\phi - \mathbf{u}) + \nu(\phi_y - v) \right] dy$$

μ, ν : Lagrange multipliers or pseudo-velocity field

GENERALIZATION OF THE LAGRANGIAN DENSITY

D. CLAMOND & D. DUTYKH, PHYS. D (2012) [CD12]

- ▶ Relaxed variational principle:

$$\mathcal{L} = (\eta_t + \tilde{\boldsymbol{\mu}} \cdot \nabla \eta - \tilde{\nu}) \check{\phi} + (\mathbf{d}_t + \check{\boldsymbol{\mu}} \cdot \nabla \mathbf{d} + \check{\nu}) \check{\phi} - \frac{1}{2} g \eta^2 + \int_{-d}^{\eta} \left[\boldsymbol{\mu} \cdot \mathbf{u} - \frac{1}{2} \mathbf{u}^2 + \nu v - \frac{1}{2} v^2 + (\nabla \cdot \boldsymbol{\mu} + \nu_y) \phi \right] dy$$

- ▶ Classical formulation (for comparison):

$$\mathcal{L} = \check{\phi} \eta_t + \check{\phi} \mathbf{d}_t - \frac{1}{2} g \eta^2 - \int_{-d}^{\eta} \left[\frac{1}{2} |\nabla \phi|^2 + \frac{1}{2} \phi_y^2 \right] dy$$

DEGREES OF FREEDOM: $\eta, \phi; \mathbf{u}, \mathbf{v}; \boldsymbol{\mu}, \nu$

SHALLOW WATER REGIME

CHOICE OF A SIMPLE ANSATZ IN SHALLOW WATER

- ▶ Ansatz:

$$\mathbf{u}(\mathbf{x}, y, t) \approx \bar{\mathbf{u}}(\mathbf{x}, t), v(\mathbf{x}, y, t) \approx (y + d)(\eta + d)^{-1} \tilde{v}(\mathbf{x}, t)$$

$$\phi(\mathbf{x}, y, t) \approx \bar{\phi}(\mathbf{x}, t), \nu(\mathbf{x}, y, t) \approx (y + d)(\eta + d)^{-1} \tilde{\nu}(\mathbf{x}, t)$$

- ▶ Lagrangian density:

$$\mathcal{L} = \bar{\phi}\eta_t - \frac{1}{2}g\eta^2 + (\eta + d) \left[\bar{\boldsymbol{\mu}} \cdot \bar{\mathbf{u}} - \frac{1}{2}\bar{u}^2 + \frac{1}{3}\tilde{v}\tilde{v} - \frac{1}{6}\tilde{v}^2 - \bar{\boldsymbol{\mu}} \cdot \nabla \bar{\phi} \right]$$

- ▶ Nonlinear Shallow Water Equations:

$$h_t + \nabla \cdot [h\bar{\mathbf{u}}] = 0,$$

$$\bar{u}_t + (\bar{\mathbf{u}} \cdot \nabla)\bar{u} + g\nabla h = 0.$$

- ▶ Not so interesting...

CONSTRAINING WITH FREE SURFACE IMPERMEABILITY

- ▶ Constraint:

$$\tilde{v} = \eta_t + \bar{\mu} \cdot \nabla \eta$$

- ▶ Generalized Serre (Green–Naghdi) equations [Ser53]:

$$h_t + \nabla \cdot [h\bar{u}] = 0,$$

$$\bar{u}_t + \bar{u} \cdot \nabla \bar{u} + g \nabla h + \frac{1}{3} h^{-1} \nabla [h^2 \tilde{\gamma}] = (\bar{u} \cdot \nabla h) \nabla (h \nabla \cdot \bar{u}) - [\bar{u} \cdot \nabla (h \nabla \cdot \bar{u})] \nabla h$$

$$\tilde{\gamma} = \tilde{v}_t + \bar{u} \cdot \nabla \tilde{v} = h((\nabla \cdot \bar{u})^2 - \nabla \cdot \bar{u}_t - \bar{u} \cdot \nabla (\nabla \cdot \bar{u}))$$

CANNOT BE OBTAINED FROM LUKE'S LAGRANGIAN:

$$\delta \bar{\mu}: \bar{u} = \nabla \bar{\phi} - \frac{1}{3} \tilde{v} \nabla \eta \neq \nabla \bar{\phi}$$

INCOMPRESSIBILITY AND PARTIAL POTENTIAL FLOW

- ▶ Ansatz and constraints ($v \neq \phi_y$):

$$\bar{\mu} = \bar{u}, \bar{v} = \tilde{v}, \bar{u} = \nabla \bar{\phi}, \tilde{v} = -(\eta + d) \nabla^2 \bar{\phi}$$

$$\mathcal{L} = \bar{\phi} \eta_t - \frac{1}{2} g \eta^2 - \frac{1}{2} (\eta + d) (\nabla \bar{\phi})^2 + \frac{1}{6} (\eta + d)^3 (\nabla^2 \bar{\phi})^2$$

- ▶ Generalized Kaup-Boussinesq equations:

$$\eta_t + \nabla \cdot [(\eta + d) \nabla \bar{\phi}] + \frac{1}{3} \nabla^2 [(\eta + d)^3 (\nabla^2 \bar{\phi})] = 0,$$

$$\bar{\phi}_t + g \eta + \frac{1}{2} (\nabla \bar{\phi})^2 - \frac{1}{2} (\eta + d)^2 (\nabla^2 \bar{\phi})^2 = 0.$$

- ▶ Hamiltonian functional:

$$\mathcal{H} = \int_{\Omega} \left\{ \frac{1}{2} g \eta^2 + \frac{1}{2} (\eta + d) (\nabla \bar{\phi})^2 - \frac{1}{6} (\eta + d)^3 (\nabla^2 \bar{\phi})^2 \right\} d\mathbf{x}$$

INCOMPRESSIBILITY AND PARTIAL POTENTIAL FLOW

- ▶ Ansatz and constraints ($v \neq \phi_y$):

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$$\mathcal{L} = \bar{\phi}\eta_t - \frac{1}{2}g\eta^2 - \frac{1}{2}(\eta + d)(\nabla \bar{\phi})^2 + \frac{1}{6}(\eta + d)^3(\nabla^2 \bar{\phi})^2$$

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$$\eta_t + \nabla \cdot [(\eta + d)\nabla \bar{\phi}] + \frac{1}{3}\nabla^2 [(\eta + d)^3(\nabla^2 \bar{\phi})] = 0,$$

$$\bar{\phi}_t + g\eta + \frac{1}{2}(\nabla \bar{\phi})^2 - \frac{1}{2}(\eta + d)^2(\nabla^2 \bar{\phi})^2 = 0.$$

- ▶ Dispersion relation ($c^2 < 0$, $\kappa d > 1/\sqrt{3}$):

$$\eta = a \cos \kappa(x - ct), \quad c^2 = gd\left(1 - \frac{1}{3}(\kappa d)^2\right)$$

DEEP WATER APPROXIMATION

- ▶ Choice of the ansatz:

$$\{\phi; \mathbf{u}; \mathbf{v}; \mu; \nu\} \approx \{\tilde{\phi}; \tilde{\mathbf{u}}; \tilde{\mathbf{v}}; \tilde{\mu}; \tilde{\nu}\} \mathbf{e}^{\kappa(y-\eta)}$$

$$2\kappa\mathcal{L} = 2\kappa\tilde{\phi}\eta_t - g\kappa\eta^2 + \frac{1}{2}\tilde{\mathbf{u}}^2 + \frac{1}{2}\tilde{\mathbf{v}}^2 - \tilde{\mathbf{u}} \cdot (\nabla\tilde{\phi} - \kappa\tilde{\phi}\nabla\eta) - \kappa\tilde{\mathbf{v}}\tilde{\phi}$$

- ▶ generalized Klein-Gordon equations:

$$\begin{aligned}\eta_t + \frac{1}{2}\kappa^{-1}\nabla^2\tilde{\phi} - \frac{1}{2}\kappa\tilde{\phi} &= \frac{1}{2}\tilde{\phi}[\nabla^2\eta + \kappa(\nabla\eta)^2] \\ \tilde{\phi}_t + g\eta &= -\frac{1}{2}\nabla \cdot [\tilde{\phi}\nabla\tilde{\phi} - \kappa\tilde{\phi}^2\nabla\eta]\end{aligned}$$

- ▶ Hamiltonian functional:

$$\mathcal{H} = \int_{\Omega} \left\{ \frac{1}{2}g\eta^2 + \frac{1}{4}\kappa^{-1}[\nabla\tilde{\phi} - \kappa\tilde{\phi}\nabla\eta]^2 + \frac{1}{4}\kappa\tilde{\phi}^2 \right\} d\mathbf{x}$$

DEEP WATER APPROXIMATION

- ▶ Choice of the ansatz:

$$\{\phi; \mathbf{u}; \mathbf{v}; \mu; \nu\} \approx \{\tilde{\phi}; \tilde{\mathbf{u}}; \tilde{\mathbf{v}}; \tilde{\mu}; \tilde{\nu}\} e^{\kappa(y-\eta)}$$

$$2\kappa\mathcal{L} = 2\kappa\tilde{\phi}\eta_t - g\kappa\eta^2 + \frac{1}{2}\tilde{\mathbf{u}}^2 + \frac{1}{2}\tilde{\mathbf{v}}^2 - \tilde{\mathbf{u}} \cdot (\nabla\tilde{\phi} - \kappa\tilde{\phi}\nabla\eta) - \kappa\tilde{\mathbf{v}}\tilde{\phi}$$

- ▶ generalized Klein-Gordon equations:

$$\begin{aligned}\eta_t + \frac{1}{2}\kappa^{-1}\nabla^2\tilde{\phi} - \frac{1}{2}\kappa\tilde{\phi} &= \frac{1}{2}\tilde{\phi}[\nabla^2\eta + \kappa(\nabla\eta)^2] \\ \tilde{\phi}_t + g\eta &= -\frac{1}{2}\nabla \cdot [\tilde{\phi}\nabla\tilde{\phi} - \kappa\tilde{\phi}^2\nabla\eta]\end{aligned}$$

- ▶ Multi-symplectic structure:

$$\mathbb{M}\mathbf{z}_t + \mathbb{K}\mathbf{z}_x + \mathbb{L}\mathbf{z}_y = \nabla_{\mathbf{z}}\mathcal{S}(\mathbf{z})$$

COMPARISON WITH EXACT STOKES WAVE

- ▶ Cubic Zakharov Equations (CZE):

$$\begin{aligned}\eta_t - \partial\tilde{\phi} &= -\nabla \cdot (\eta\nabla\tilde{\phi}) - \partial(\eta\partial\tilde{\phi}) + \\ &\quad \frac{1}{2}\nabla^2(\eta^2\partial\tilde{\phi}) + \partial(\eta\partial(\eta\partial\tilde{\phi})) + \frac{1}{2}\partial(\eta^2\nabla^2\tilde{\phi}), \\ \tilde{\phi}_t + g\eta &= \frac{1}{2}(\partial\tilde{\phi})^2 - \frac{1}{2}(\nabla\tilde{\phi})^2 - (\eta\partial\tilde{\phi})\nabla^2\tilde{\phi} - (\partial\tilde{\phi})\partial(\eta\partial\tilde{\phi}).\end{aligned}$$

- ▶ Phase speed :

$$\text{EXACT: } g^{-\frac{1}{2}}\kappa^{\frac{1}{2}} \mathbf{c} = 1 + \frac{1}{2}\alpha^2 + \frac{1}{2}\alpha^4 + \frac{707}{384}\alpha^6 + O(\alpha^8)$$

$$\text{CZE: } g^{-\frac{1}{2}}\kappa^{\frac{1}{2}} \mathbf{c} = 1 + \frac{1}{2}\alpha^2 + \frac{41}{64}\alpha^4 + \frac{913}{384}\alpha^6 + O(\alpha^8)$$

$$\text{gKG: } g^{-\frac{1}{2}}\kappa^{\frac{1}{2}} \mathbf{c} = 1 + \frac{1}{2}\alpha^2 + \frac{1}{2}\alpha^4 + \frac{899}{384}\alpha^6 + O(\alpha^8)$$

- ▶ n -th Fourier coefficient to the leading order: $\frac{n^{n-2}\alpha^n}{2^{n-1}(n-1)!}$ (the same in gKG & Stokes but not in CZE)

DEEP-WATER SERRE–GREEN–NAGHDI EQUATIONS

CONSTRAINING WITH THE FREE-SURFACE IMPERMEABILITY

- ▶ Additional constraint:

$$\tilde{v} = \eta_t + \tilde{\mathbf{u}} \cdot \nabla \eta$$

- ▶ Lagrangian density reads:

$$2\kappa \mathcal{L} = \tilde{\phi} (\kappa \eta_t + \nabla \cdot \tilde{\mathbf{u}}) - g\kappa \eta^2 + \frac{1}{2} \tilde{\mathbf{u}}^2 + \frac{1}{2} (\eta_t + \tilde{\mathbf{u}} \cdot \nabla \eta)^2$$

$$\delta \tilde{\mathbf{u}} : \quad \mathbf{0} = \tilde{\mathbf{u}} + (\eta_t + \tilde{\mathbf{u}} \cdot \nabla \eta) \nabla \eta - \nabla \tilde{\phi},$$

$$\delta \tilde{\phi} : \quad 0 = \kappa \eta_t + \nabla \cdot \tilde{\mathbf{u}},$$

$$\delta \eta : \quad 0 = 2g\kappa \eta + \kappa \tilde{\phi}_t + \eta_{tt} + (\tilde{\mathbf{u}} \cdot \nabla \eta)_t + \nabla \cdot (\tilde{\mathbf{u}} \eta_t) + \nabla \cdot [(\tilde{\mathbf{u}} \cdot \nabla \eta) \tilde{\mathbf{u}}]$$

- ▶ Cannot be derived from Luke's Lagrangian:

$$\nabla \tilde{\phi} = \tilde{\mathbf{u}} + \tilde{v} \nabla \eta$$

DEEP-WATER SERRE–GREEN–NAGHDI EQUATIONS

CONSTRAINING WITH THE FREE-SURFACE IMPERMEABILITY

- ▶ Additional constraint:

$$\tilde{v} = \eta_t + \tilde{\mathbf{u}} \cdot \nabla \eta$$

- ▶ Lagrangian density reads:

$$2\kappa \mathcal{L} = \tilde{\phi} (\kappa \eta_t + \nabla \cdot \tilde{\mathbf{u}}) - g\kappa \eta^2 + \frac{1}{2} \tilde{\mathbf{u}}^2 + \frac{1}{2} (\eta_t + \tilde{\mathbf{u}} \cdot \nabla \eta)^2$$

$$\delta \tilde{\mathbf{u}} : \quad \mathbf{0} = \tilde{\mathbf{u}} + (\eta_t + \tilde{\mathbf{u}} \cdot \nabla \eta) \nabla \eta - \nabla \tilde{\phi},$$

$$\delta \tilde{\phi} : \quad 0 = \kappa \eta_t + \nabla \cdot \tilde{\mathbf{u}},$$

$$\delta \eta : \quad 0 = 2g\kappa \eta + \kappa \tilde{\phi}_t + \eta_{tt} + (\tilde{\mathbf{u}} \cdot \nabla \eta)_t + \nabla \cdot (\tilde{\mathbf{u}} \eta_t) + \nabla \cdot [(\tilde{\mathbf{u}} \cdot \nabla \eta) \tilde{\mathbf{u}}]$$

- ▶ Incompressibility is satisfied identically:

$$0 = \kappa \eta_t + \nabla \cdot \tilde{\mathbf{u}} \iff \nabla \cdot \mathbf{u} + v_y = 0$$

DEEP-WATER SERRE–GREEN–NAGHDI EQUATIONS

CONSTRAINING WITH THE FREE-SURFACE IMPERMEABILITY

- ▶ Additional constraint:

$$\tilde{\mathbf{v}} = \eta_t + \tilde{\mathbf{u}} \cdot \nabla \eta$$

- ▶ Lagrangian density reads:

$$2\kappa \mathcal{L} = \tilde{\phi} (\kappa \eta_t + \nabla \cdot \tilde{\mathbf{u}}) - g\kappa \eta^2 + \frac{1}{2} \tilde{\mathbf{u}}^2 + \frac{1}{2} (\eta_t + \tilde{\mathbf{u}} \cdot \nabla \eta)^2$$

$$\delta \tilde{\mathbf{u}} : \quad \mathbf{0} = \tilde{\mathbf{u}} + (\eta_t + \tilde{\mathbf{u}} \cdot \nabla \eta) \nabla \eta - \nabla \tilde{\phi},$$

$$\delta \tilde{\phi} : \quad 0 = \kappa \eta_t + \nabla \cdot \tilde{\mathbf{u}},$$

$$\delta \eta : \quad 0 = 2g\kappa \eta + \kappa \tilde{\phi}_t + \eta_{tt} + (\tilde{\mathbf{u}} \cdot \nabla \eta)_t + \nabla \cdot (\tilde{\mathbf{u}} \eta_t) + \nabla \cdot [(\tilde{\mathbf{u}} \cdot \nabla \eta) \tilde{\mathbf{u}}]$$

- ▶ Exact dispersion relation if $k = \kappa$:

$$\eta = a \cos k(x_1 - ct), \quad c^2 = 2g\kappa (k^2 + \kappa^2)^{-1}$$

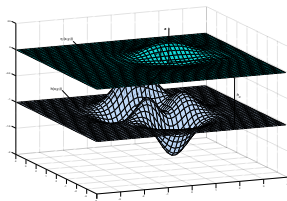
ARBITRARY DEPTH CASE

NO AVAILABLE SMALL PARAMETERS...

- ▶ Finite depth ansatz:

$$\phi \approx \frac{\cosh \kappa Y}{\cosh \kappa h} \tilde{\phi}(\mathbf{x}, t), \quad \mathbf{u} \approx \frac{\cosh \kappa Y}{\cosh \kappa h} \tilde{\mathbf{u}}(\mathbf{x}, t),$$

$$\boldsymbol{\mu} \approx \frac{\cosh \kappa Y}{\cosh \kappa h} \tilde{\boldsymbol{\mu}}(\mathbf{x}, t), \quad \nu \approx \frac{\sinh \kappa Y}{\sinh \kappa h} \tilde{\nu}(\mathbf{x}, t).$$



- ▶ Finite depth Lagrangian:

$$\begin{aligned} \mathcal{L} = & [\eta_t + \tilde{\boldsymbol{\mu}} \cdot \nabla \eta] \tilde{\phi} - \frac{1}{2} g \eta^2 + [\tilde{\nu} \tilde{\nu} - \frac{1}{2} \tilde{\nu}^2] \frac{\sinh(2\kappa h) - 2\kappa h}{2\kappa \cosh(2\kappa h) - 2\kappa} \\ & + [\tilde{\boldsymbol{\mu}} \cdot \tilde{\mathbf{u}} - \frac{1}{2} \tilde{\mathbf{u}}^2 + \tilde{\phi} \nabla \cdot \tilde{\boldsymbol{\mu}} - \kappa \tanh(\kappa h) \tilde{\phi} \tilde{\boldsymbol{\mu}} \cdot \nabla \eta] \frac{\sinh(2\kappa h) + 2\kappa h}{2\kappa \cosh(2\kappa h) + 2\kappa} \\ & + \frac{1}{2} \tilde{\phi} \tilde{\nu} \left[\frac{2\kappa h}{\sinh(2\kappa h)} - 1 \right]. \end{aligned}$$

CONCLUSIONS & PERSPECTIVES

CONCLUSIONS:

- ▶ A relaxed variational principle was presented
- ▶ Practical usage of this principle was illustrated
- ▶ All models automatically possess the Lagrangian structure
 - ▶ In most cases the Hamiltonian as well!



PERSPECTIVES:

- ▶ Further validation of derived models is needed
- ▶ Deeper study of their properties
- ▶ Development of variational discretizations

Thank you for your attention!



<http://www.denys-dutykh.com/>

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